THE MEASURABLE DIFFERENCE.



OXYGEN TRAINING > GPS DATA ACQUISITION

DEWETRON

PUBLIC

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TRION MODULES FOR GPS-DAQ

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1

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2

	GPS 1/1 Sim GPS 1/1 TRION-VGPS-100-V3	¢			nan	NMEA	100 Hz		
	Latitude_GPS 1/1 Sim OPS 1/1 Sim OPS Latitude	ø			NaN XAVG	Latitude	100 Hz	-90 ° 90 °	
> Max. 10 Hz refresh rate	Longitude_GPS 1/1 Sim OPS 1/1 Sim OPS Longitude	۲		٥	NaN ¥AVG	Longitude	100 Hz	-180 ° 180 °	
	Altitude_GPS 1/1 Sim 0P5 1/1 Sim 0P5 Albitude	۵			NaN 2AVG	Altitude	100 Hz	-100 m 1000 m	
TRION-VGPS-20	Velocity_GPS 1/1 Sim OPS 1/1 Sim OPS Velocity Heading GPS 1/1 Sim	*		0	NaN ¥AVG NaN ¥AVG	Velocity	100 Hz	0 km/h 300 km/h	
Nov 2011 refresh rete	GPS 1/1 Sim GPS Direction Satellites_GPS 1/1 Sim	@ 			NaN XAVG	Direction	100 Hz	0 ~ 360 ~	
> Widx. 20 HZ refresh rate	GPS 1/1 Sim GPS Satellites	*			o 24 nan	Quality	100 Hz	0.1.24	
	H. Dilution_GPS 1/1 Sim GPS 1/1 Sim GPS HDOP	۲		0	NaN ZAVG	HDOP	100 Hz	0 m 100 m	
	SoD_GPS 1/1 Sim GPS 1/1 Sim GPS Second	۲		٥	NaN XAVG	Second	100 Hz	0 s 86400 s	
	Date_GPS 1/1 Sim GPS 1/1 Sim GPS Date	۲		0	nan	Date	100 Hz		
> Max. 100 Hz refresh rate	Acceleration_GPS 1/1 Sim 0PS 1/1 Sim 0PS Acceleration	۵ (NaN 2AVG	Acceleration	100 Hz	-1000 m/s ² 1000 m/s ²)
	OPS 1/1 Sim OPS Distance	÷			0 100000	Distance	100 Hz	0 m 1000000 m	
Data acquired by the GPS receiver	Default Channel Name	Data		Channel description		Range	Unit		
	GPS	NMEA		GPS NMEA channel		-	-		
	Latitude_GPS	Latitude		Current latitude of the object		-90° 90°	•		
> Longitude	Longitude_GPS	Longitude		Current longitude of the object		-180° 180°	m		
Altitudo	Velocity GPS	Velocity		Current velocity of the object		0 km/h 300 km/h	km/h		
Annue	Heading_GPS	Direction		Current heading of the object			0° 360°	•	
> Velocity	Satellites_GPS	Satellites		Number of satellites in view		0 24	-		
> Heading	Fix Quality_GPS	Quality		GPS Fix Quality		•	-		
	H. Dilution_GPS	HDOP		2D deviation of longitude and latitude		0m 100 m	m		
> Satellites	SoD_GPS	Second		Current second of the day		0s 86400 s	m		
> Fix Quality	Date_GPS	Date		Current date in the format yyy-mm-dd hh:mm:ss:ms			-	-	
> H. Dilution	Acceleration_GPS	Acceleration		Current acceleration of the object			-1000 m/s ² 1000 m/s ²	m/s²	
> SoD; Seconds of Day	Distance_GPS	Distance		Distance covered from start of measurement			0m 1000000 m	m	

Date

(1)

(2)

3

- > Acceleration (Calculated from Velocity)
- > Distance (Calculated from Velocity)

2

GPS PLOT INSTRUMENT



For visualizing the current position and the travelled track, the GPS plot can be used

- 1 The GPS plot can be dragged and dropped from the Instruments menu
- 2 Latitude, Longitude and Heading can be assigned to the GPS plot instrument
- In case a internet connection is active, an
 Open Street Map from the current
 position is automatically loaded





Map © WikiMedia Foundation | Data © OpenStreetMap contributors

GPS PLOT INSTRUMENT

(4)

(5)

(6)



GPS QUALITY INSTRUMENT



DEWETRON Data Channels Displays the Position of the satellites in ø Selected instrument only view and gives an overview of the -f current GPS data Ń DI 1/1 Sim January DI 1/2 Sim Instruments (1)Can be added to the measurement DI 1/3 Sim DI 1/4 Sim screen by dragging and dropping the GPS -----Spectrum analyze Video DI 1/5 Sim GmbH | NMEA string to the screen... DI 1/6 Sim -GPS GPS plot di di ħ. 354.7 m DI 1/7 Sim XYplot (2)DI 1/8 Sim ... or by selecting the *GPS quality* CNT 1/1 Sim DEWETRON Non վերի instrument form the Instrument and {CNT 1/1 Sim} Spectrogram {Frequency...T 1/1 Sim} assigning the GPS NMEA string Angle_CNT 1/1 Sim 金康 afterwards Speed CNT 1/1 Sim Intensity diagram {GPS 1/1 Sim] \odot (3) Explanation of the *satellites* plot BirdsEve SCREEN Zenith 3 Celesti Mathematical Elevation [°] Altitude X 30 65 Observer Horizon Azimut

SNR [%]