# TRION-1802/1600-dLV-32



## TRION-1802/1600-dLV-32

- Multi-function module with voltage inputs, digital I/Os, counter and CAN
- Channels: 32 single-ended or 16 differential, synchronous channels
- Sampling
  - TRION-1802-dLV-32: 18-bit; 200 kS/s per channel
  - TRION-1600-dLV-32: 16-bit; 20 kS/s per channel
- Input type: 5 V/10 V
- Features: 2x counter; CAN bus; RS-485; 8x DI; 4x DO

### Module specifications

### TRION-1802/1600-dLV-32 specifications

Input channels		TRION-1802-dLV-32	32 channels single-ended or 16 channels fully differential	
		TRION-1802-dLV-32-CAN	32 channels single-ended or 16 channels fully differential + CAN	
		TRION-1600-dLV-32	32 channels single-ended or 16 channels fully differential	
		TRION-1600-dLV-32-CAN	32 channels single-ended or 16 channels fully differential + CAN	
Sampling rate / resolution		TRION-1802-dLV-32	Highspeed mode: >50 to 200 kS/s, 18-bit	
			Over-sampling mode: 100 S/s to 20 kS/s, 24-bit	
		TRION-1600-dLV-32	100 S/s to 20 kS/s 16-bit	
Data transfer		TRION-1802-dLV-32: 16-bit / 24-bit / 32-bit		
		TRION-1600-dLV-32: 16-bit		
Onboard data buffer		512 MB		
ADC type		18-bit SAR <sup>2)</sup> (Successive Approximation Register)		
Data rate DMA transfer		32 analog channels: max 28 MB/s; 2x counter: max. 6 MB/s		
Input ranges				
– Voltage		±5 V, ±10 V		
Input noise (5 mV range)				
- 0 to 10 Hz		10 µV <sub>PP</sub>		
<ul> <li>Full bandwidth</li> </ul>		1.35 mV <sub>pp</sub>		
Input impedance		1 M $\Omega$ single-ended, 2 M $\Omega$ differential		
Input bias current		<25 pA		
Input coupling		DC		
	Voltage	DC to 1 kHz ±	0.02 % of reading ± 0.01 % of range ±20 μV	
Accuracy <sup>1)</sup>		>1 kHz to 5 kHz ±	0.5 % of reading ± 0.01 % of range ±20 $\mu$ V	
		>5 kHz to 10 kHz <sup>2)</sup> ±	1 % of reading ± 0.01 % of range ±20 $\mu V$	
Gain drift		Typical 10 ppm/°C max. 20 ppm/°C		
Offset drift		Typical 0.3 $\mu$ V/°C + 10 ppm of range/°C, max 15 $\mu$ V/°C + 20 ppm of range/°C		
Linearity		<20 ppm		

Tab. 33: Module specifications

# TRION-1802/1600-dLV-32



#### TRION-1802/1600-dLV-32 specifications

Typical signal-to-noise ratio, spurious	10 V range					
Free SNR, effective number of Bits, $V_{_{PP}}^{^{2)}}$	SNR	SFDR <sup>3)</sup>	ENOB <sup>4)</sup>	Noise peak to peak		
Sample rate	[dB]	[dB]	[Bit]	[mV <sub>PP</sub> ]		
0.1 kS/s	127	130	20.8	0.015		
1 kS/s	118	130	19.3	0.055		
10 kS/s	109	130	17.8	0.22		
20 kS/s	106	130	17.3	0.33		
50 kS/s <sup>2)</sup>	1022)	130 <sup>2)</sup>	16.7	0.52 <sup>5)</sup>		
100 kS/s <sup>2)</sup>	99 <sup>2)</sup>	130 <sup>2)</sup>	16.2	0.665)		
200 kS/s <sup>2)</sup>	96 <sup>2)</sup>	125 <sup>2)</sup>	15.7	1.00 <sup>5)</sup>		
Input configuration	Differential or single-ended with GND sense					
Typical THD	-95 dB					
Typical CMR in differential mode	100 dB @ 50 Hz; >70 dB @ 1 kHz					
Low pass filter (-3 dB, dig.)	1 Hz to 40 % of sample rate freely programmable or OFF					
<ul> <li>Characteristic</li> </ul>	Bessel or Butterworth					
– Filter order	2 <sup>nd</sup> , 4 <sup>th</sup> , 6 <sup>th</sup> , 8 <sup>th</sup>					
Analog antialiasing filter	2 <sup>rd</sup> order Butterworth					
Bandwidth (-3 dB, deacti- vated digital filter)	70 kHz 3 <sup>rd</sup> order Butterworth filter					
Crosstalk fin 1 kHz [10 kHz]	>108 dB					
Channel-to-channel phase mismatch	Typically <30 ns when using the same input range					
Board-to-board phase mismatch	ard phase <30 ns					
Common mode voltage	:12.5 V <sub>pc</sub>					
Overvoltage protection	±50 V <sub>DC</sub>	50 V <sub>DC</sub>				
	Digital Input	8 CMOS/TTL co kΩ	mpatible digital inpu	ıts; weak pullup via 100		
	Overvoltage protectio	n ±30 V <sub>DC</sub> , 50 V <sub>PEAP</sub>	±30 V <sub>DC</sub> , 50 V <sub>PEAK</sub> (for 100 ms)			
	Counter	2 counter chan	2 counter channels; TTL input; shared with digital inputs			
	<ul> <li>Counter resolution</li> </ul>	n 32-bit	32-bit			
	<ul> <li>Counter time bas</li> </ul>	e 80 MHz				
Digital IN specification	– Max. input freq.	10 MHz	10 MHz			
	Counter modes					
	<ul> <li>Waveform timing</li> </ul>	Period, frequen	cy, pulse width duty	v cycle and edge separation		
	– Sensor modes	Encoder (angle	Encoder (angle and linear)			
	<ul> <li>Event counting</li> </ul>	Basic event cou	nting, gated countin	g. up/down counting and		
	encoder mode (X1, X2 and X4)					

Tab. 33: Module specifications

## TRION-1802/1600-dLV-32



TRION-1802/1600-dLV-32 specifications						
	Digital output	4 DO; TTL				
Digital OUT specification	Output indication	LED (green = high; off = low)				
Digital OOT specification	Maximum current	25 mA continuously				
	Power-on default	Low				
	CAN bus	1 CAN Bus; not isolated; routed to D-SUB-25				
	<ul> <li>CAN specification</li> </ul>	CAN 2.0B				
	<ul> <li>CAN Physical Layer</li> </ul>	Highspeed				
Interfaces	<ul> <li>Bus pin fault protection</li> </ul>	±36 V <sub>DC</sub>				
	<ul> <li>Termination</li> </ul>	Programmable: High impedance or 120 $\boldsymbol{\Omega}$				
	– RS485	1 RS485 interface dedicated to DAQP and HSI series modules				
	Sensor power supply (per module)	5 V (600 mA) and 12 V (600 mA)				
General specification	ESD protection	IEC61000-4-2: ±8 kV air discharge, ±4 kV contact dis- charge				
	Power consumption	Voltage mode: 6 W				

### Tab. 33: Module specifications

1) 1 year accuracy 23  $^\circ\text{C}$  ±5  $^\circ\text{C}$ 

2) LP Filter in auto mode

3) SFDR excluding harmonics

4) ENOB calculated from SNR

5) TRION-1802-dLV-32 only